

PHY 610 QFT, Spring 2015

Midterm Solutions

1. (a) There is a $U(1)$ symmetry acting as $\varphi_1 \mapsto e^{i\theta}\varphi_1, \varphi_1^* \mapsto e^{-i\theta}\varphi_1^*, \varphi_2 \mapsto e^{-i\theta}\varphi_2, \varphi_2^* \mapsto e^{i\theta}\varphi_2^*$.
- (b) Using either $j^\mu = (\partial\mathcal{L}/\partial\partial_\mu\varphi)\delta\varphi$, or varying the action under a spacetime dependent symmetry transformation $\theta(x)$, and collecting the coefficient of $\partial_\mu\theta$, we get

$$j^\mu = i(\varphi_1\partial^\mu\varphi_1^* - \partial^\mu\varphi_1\varphi_1^* - \varphi_2\partial^\mu\varphi_2^* + \partial^\mu\varphi_2\varphi_2^*).$$

The Noether charge is

$$Q = \int d^3x i(\varphi_1\partial^0\varphi_1^* - \partial^0\varphi_1\varphi_1^* - \varphi_2\partial^0\varphi_2^* + \partial^0\varphi_2\varphi_2^*).$$

Substituting the mode expansions

$$\varphi_j(x) = \int \frac{d^3k}{(2\pi)^3 2\omega_{\mathbf{k}}} (a_j(\mathbf{k})e^{ikx} + b_j^\dagger(\mathbf{k})e^{-ikx}), \quad j = 1, 2$$

yields

$$Q = \int \frac{d^3k}{(2\pi)^3 2\omega_{\mathbf{k}}} (a_1^\dagger(\mathbf{k})a_1(\mathbf{k}) - b_1(\mathbf{k})b_1^\dagger(\mathbf{k}) - a_2^\dagger(\mathbf{k})a_2(\mathbf{k}) + b_2(\mathbf{k})b_2^\dagger(\mathbf{k})),$$

that is, the Noether charge counts the difference between the number of φ_1 and φ_2 particles (with antiparticles contributing opposite signs).

- (c) At $\mu = 0$ there is a $U(1) \times U(1)$ symmetry, acting as $\varphi_1 \mapsto e^{i\theta_1}\varphi_1, \varphi_2 \mapsto e^{i\theta_2}\varphi_2$.
- (d) When $\mu = 0, m_1 = m_2$, the symmetry is enhanced to an $SO(4)$ symmetry rotating $\varphi_j := (\Re\varphi_1, \Im\varphi_1, \Re\varphi_2, \Im\varphi_2)$. The Noether current is

$$j_a^\mu = i\partial^\mu\varphi_i(T_a)_{ij}\varphi_j,$$

where $(T_a)_{ij}$ are the (hermitian) generators of $SO(4)$ in the defining representation.

2. (a) $\langle 0|T A(x)A(y)|0\rangle =$

$$+ \frac{x}{z_1 z_2} \frac{y}{z_1 z_2} + O[\lambda]^4$$

$= \Delta_{xy} - \lambda^2 \left(\alpha^2 \int d^4z_1 d^4z_2 \Delta_{x1}\Delta_{12}\Delta_{12}\Delta_{2y} + \frac{1}{2}\Delta_{x1}\Delta_{12}\Delta_{22}\Delta_{1y} + \frac{1}{4}\Delta_{xy}\Delta_{12}^2\Delta_{12} + \frac{1}{8}\Delta_{xy}\Delta_{11}\Delta_{12}\Delta_{22} + i\beta \int d^4z_1 \frac{1}{8}\Delta_{xy}\Delta_{11}^2 \right) + O[\lambda^4]$

$$\begin{aligned}
 \langle 0 | TB(x) B(y) | 0 \rangle &= \text{---}^x \text{---}^y + \text{---}^x \text{---}^y \text{---}^z_1 \text{---}^z_2 + \text{---}^x \text{---}^y \text{---}^z_1 \text{---}^z_2 + \text{---}^x \text{---}^y \\
 &+ \text{---}^x \text{---}^y \text{---}^z_1 \text{---}^z_2 + \text{---}^x \text{---}^y \text{---}^z_1 \text{---}^z_2 + \text{---}^x \text{---}^y \\
 &= \Delta_{xy} - \lambda^2 \left(\alpha^2 \int d^4 z_1 d^4 z_2 \frac{1}{2} \Delta_{x1} \Delta_{12} \Delta_{12} \Delta_{2y} + \frac{1}{4} \Delta_{x1} \Delta_{11} \Delta_{22} \Delta_{2y} + \frac{1}{4} \Delta_{xy} \Delta_{12}^2 \Delta_{12} + \frac{1}{8} \Delta_{xy} \Delta_{11} \Delta_{12} \Delta_{22} \right. \\
 &\quad \left. + i\beta \int d^4 z_1 \frac{1}{2} \Delta_{x1} \Delta_{11} \Delta_{1y} + \frac{1}{8} \Delta_{xy} \Delta_{11}^2 \right) + O[\lambda^4]
 \end{aligned}$$

(b) i. $AA \rightarrow BB$

$$\begin{aligned}
 i\mathcal{T} &= \text{---} \text{---} \text{---} + \text{---} \text{---} \text{---} \\
 &= (i\alpha\lambda)^2 \left(\frac{i}{t-m^2+i\epsilon} + \frac{i}{u-m^2+i\epsilon} \right)
 \end{aligned}$$

ii. $AA \rightarrow AA$

$$\begin{aligned}
 i\mathcal{T} &= \text{---} \text{---} \text{---} + \text{---} \text{---} \text{---} + \text{---} \text{---} \text{---} \\
 &= (i\alpha\lambda)^2 \left(\frac{i}{s-m^2+i\epsilon} + \frac{i}{t-m^2+i\epsilon} + \frac{i}{u-m^2+i\epsilon} \right).
 \end{aligned}$$

iii. $AB \rightarrow AB$

$$\begin{aligned}
 i\mathcal{T} &= \text{---} \text{---} \text{---} + \text{---} \text{---} \text{---} \\
 &= (i\alpha\lambda)^2 \left(\frac{i}{s-m^2+i\epsilon} + \frac{i}{u-m^2+i\epsilon} \right)
 \end{aligned}$$

iv. $BB \rightarrow BB$

$$\begin{aligned}
 i\mathcal{T} &= \text{---} \text{---} \text{---} \\
 &= -i\beta\lambda^2.
 \end{aligned}$$